

Scara Robot



Model **P40-804S**

Operating range Arm length 800mm Joint#3 stroke 420mm

Rated 20kg/Maximum 40kg Payload

Standard cycle time 0.43 sec



Cycle time based on round-trip arch motion (300mm horizontal,25mm vertical) with 2kg payload (path coordinates optimized for maximum speed)

 \pm 0.025mm \pm 0.01mm $\pm 0.01^{\circ}$ Repeatability Joint #1,#2 Joint #3 Joint #4

Parameters of each axis

Joint Content	#1	#2	#3	#4
MAX Operating Speed	8271 mm/s		2020mm/s	1400° /s
MAX Motion Range	±131°	±150°	420mm	±360°
Motor Power Consumption	1000W	750W	400W	400W
Joint#3 down force			250N	
Weight	49kg(cables not included)			

Joint #4 allowable moment of inertia, rate 0.05kg·m², maximum 0.45kg·m²

None Need Origin Return Electrical parameters Origin Return

> 26 Pin (D-Sub Connector) Installed wire for customer

Installed pneumatic tube for customer use

Visual Interface

M12*2 Gigabit network interface

φ4mm*2, φ6mm*2

Installation Environment Standerd/Clean (Customized)

www.sharewell.cc

Outer Dimensions and Motion Range

2 x M4 through hole 4 x ⊕ 16 through hole





