P40 series/ Scara Robot



Model **P40-904S**

Rated 20kg/Maximum 40kg Payload

Standard cycle time 0.46 sec



Cycle time based on round-trip arch motion (300mm horizontal,25mm vertical) with 2kg payload (path coordinates optimized for maximum speed)

 \pm 0.01mm $\pm 0.01^{\circ}$ Repeatability \pm 0.025mm Joint #1,#2 Joint #3 Joint #4

Parameters of each axis

Joint Content	#1	#2	#3	#4
MAX Operating Speed	8878 mm/s		2020mm/s	1400° /s
MAX Motion Range	±131°	±150°	420mm	±360°
Motor Power Consumption	1000W	750W	400W	400W
Joint#3 down force			250N	
Weight	52kg (cables not included)			

Joint #4 allowable moment of inertia, rate 0.05kg·m², maximum 0.45kg·m²

None Need Origin Return Electrical parameters Origin Return

> 26 Pin (D-Sub Connector) Installed wire for customer

Installed pneumatic tube for customer use

φ4mm*2, φ6mm*2

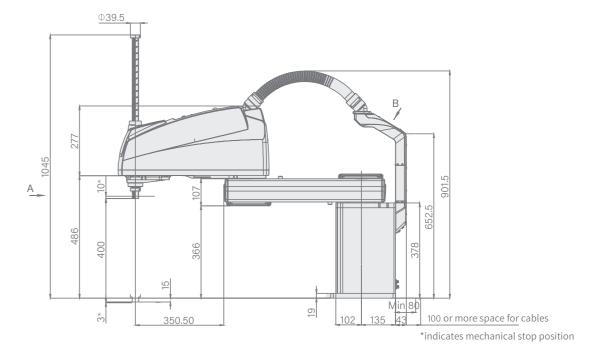
Visual Interface M12*2 Gigabit network interface

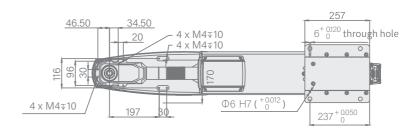
Installation Environment Standerd/Clean (Customized)

Operating range Arm length900mm Joint#3 stroke 420mm

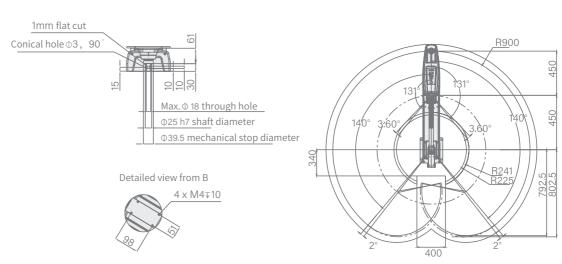
2 x M4 through hole 4 x ⊕ 16 through hole

Outer Dimensions and Motion Range





Detailed view from A



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