P10 series/

Scara Robot



Model P10-8025 / P10-8035

Operating range Arm length800mm Joint#3 stroke200/300mm

Payload Rated 5kg/Maximum 10kg

Standard cycle time 0.449 sec



Cycle time based on round-trip arch motion (300mm horizontal,25mm vertical) with 2kg payload (path coordinates optimized for maximum speed)

Repeatability ± 0.025 mm ± 0.01 mm $\pm 0.01^{\circ}$ Joint #1,#2 Joint #3 Joint #4

Parameters of each axis

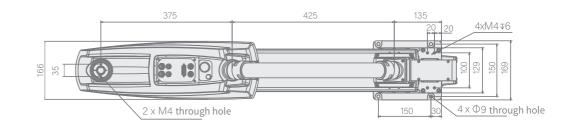
Joint Content	#1	#2	#3	#4
MAX Operating Speed	10600 mm/s		1098mm/s	1581°/s
MAX Motion Range	±132°	±152°	200mm 300mm	±360°
Motor Power Consumption	750W	750W	400W	400W
Joint#3 down force			250N	
Weight	32kg (cables not included)			

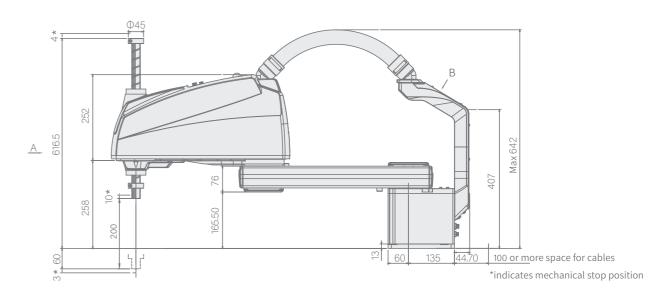
Joint #4 allowable moment of inertia, rate 0.02kg⋅m², maximum 0.3kg⋅m²

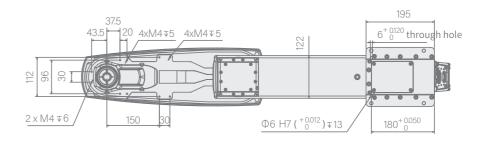
Electrical parameters
Origin Return
None Need Origin Return
Installed wire for customer
26 Pin (D-Sub Connector)
Installed pneumatic tube for customer use
Visual Interface
M12*2 Gigabit network interface

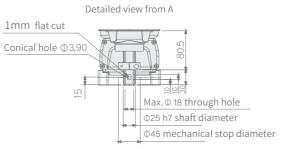
Installation Environment Standerd/Clean (Customized)

Outer Dimensions and Motion Range









r diameter 2° R200\ R213\ 2°

